February 21, 2013

Difference Calculus

Motivation

Discrete calculus (or Finite Calculus, or Calculus of Finite Differences) is the analogue of continuous calculus. It deals with spaces and processes that are discrete instead of continuous in nature. Its methods involve the same sort of operations on real numbers like those used in the calculus of real variables, but without taking limits. So instead of differentiation, discrete calculus does differencing; and instead of integration, discrete calculus does summing. The sum operator solves problems like the following quickly: find closed-form formulas for $\sum_{k=1}^{n} k^3$, for $\sum_{x=1}^{m} \sum_{y=1}^{n} (x+y)^2$, or for $\sum_{k=0}^{n} k2^k$. This application to solving sums is our main motivation for studying the subject. Finite difference methods are also used for polynomial interpolation and numerical approximation of differential equations, but we won't spend much time on this latter application.

Functions and Operators

A function f from a domain A to a codomain B, written $f:A\to B$, is a rule that associates each element $x\in A$ to exactly one element in B. The element of B associated with x is called the *image of* x *under* f and is written f(x). We usually use f, g, h, etc. to denote functions.

The functions of Finite Calculus may have as its domain some subset of the nonnegative

integers \mathbb{N} , the integers \mathbb{Z} , the real numbers \mathbb{R} , or the complex numbers \mathbb{C} , and they take values in the reals \mathbb{R} or complex numbers \mathbb{C} .

Functions on \mathbb{N} are called *sequences* and we usually use subscript notation to denote them, e.g., $\langle a_0, a_1, a_2, \dots \rangle$, or $\{a_n\}_{n=0}^{\infty}$, or $\{a_n\}_0^{\infty}$, or even $\{a_n\}$.

Two functions f and g are called *equal*, written f = g, if they have the same domain and f(x) = g(x) for all x in the common domain. Equality of functions is an equivalence relation. (Prove!)

The composition of f and g, written $f \circ g$, is a function defined by $(f \circ g)(x) = f(g(x))$ for all x. Function composition is associative, but is usually not commutative. (Prove!)

The function 1 (or I) is the identity function if 1(x) = x for all x.

A function g is called the *inverse* of f if $f \circ g = g \circ f = 1$. we write f^{-1} for the inverse of f. A function f has an inverse function iff f is bijective, i.e., 1-1 and onto.

Define $f^0 = f$ and for all nonnegative integer n, define $f^{n+1} = f \circ f^n$. If f has an inverse, we can define a function to a negative exponent by declaring $f^{-n-1} = f^{-1} \circ f^{-n}$ for all negative integer n. Function exponentiation follows the usual rules of exponents, e.g., $f^m \circ f^n = f^{m+n}$. Moreover, the set $\{f^n : n \in \mathbb{Z}\}$ commutes under composition.

We define addition, subtraction, multiplication, division, exponentiation, logarithm, etc. of real-valued (complex-valued) functions pointwise, e.g., (f+g)(x) = f(x) + g(x) for all x, etc.

Therefore, +, -, *, /, etc. of real-valued (complex-valued) functions obey the same laws as the real (and complex) numbers, e.g., + and * are associative, commutative; * distributes over +, etc. We use the same symbols for corresponding elements and operations, e.g., 0 is the identity function for +, and 1 is the identity function for *. In fact, for any $c \in \mathbb{R}$, the symbol c denotes the constant function where c(x) = c for all x.

We define scalar multiplication of a function f by a scalar α by $(\alpha f)(x) = \alpha \cdot f(x)$ for all $x \in \mathbb{R}$. Under function addition and scalar multiplication, the set of real-valued functions forms a vector space.

Difference Operator

For our purpose, we define an *operator* to be a function whose domain and codomain are sets of real-valued functions. Later we will learn that discrete calculus is interesting when the functions operated by these operators are sequences. Here are some example operators.

In continuous calculus, we studied the differential operator D or $\frac{d}{dx}$ defined as

$$Df(x) = \frac{d}{dx}f(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$
 for all x

for any differentiable real-valued function f. In this section we study an operator Δ of discrete calculus that corresponds to the D operator of continuous calculus.

The shift operator E maps a function f to the function Ef, where Ef(x) = f(x+1) for all x in the domain of f.

Recall that the *identity operator* 1 (or I) is such that 1f = f for every function f.

The forward difference operator Δ is defined to be $\Delta = E - I$, i.e.,

$$\Delta f(x) = f(x+1) - f(x)$$

for all function f and all x in the domain of f. Intuitively, in the definition for derivative, we let h approach 0 discretely, through positive integral values, and the closest that h can get to 0 without being equal to it is 1.

Theorem. (i)
$$\Delta(f \pm g) = \Delta f \pm \Delta g$$

(ii)
$$\Delta(\alpha \cdot f) = \alpha \cdot \Delta f$$

(iii)
$$\Delta(f \cdot g) = Ef \cdot \Delta g + \Delta f \cdot g = \Delta f \cdot Eg + f \cdot \Delta g$$

(iv)
$$\Delta(f/g) = \frac{\Delta f \cdot g - f \cdot \Delta g}{g \cdot Eg}$$
 where $g, Eg \neq 0$

$$Proof.$$
 ...

An operator A is *linear* if the following two conditions are satisfied:

(i)
$$A(f+g) = A(f) + A(g)$$
 for all functions f, g .

(ii)
$$A(\alpha f) = \alpha A(f)$$
 for all scalar α and function f .

One corollary of the above theorem is that Δ is a linear operator.

Notational Shorthand

Statements like $\frac{d}{dx}x^2 = 2x$ or $Dx^2 = 2x$ in differential calculus is an abuse of notation. What they actually say is that if f is a function defined by $f(x) = x^2$ for all x, then its derivative Df is the function defined by Df(x) = 2x for all x. However, this abused notation is so widespread that we'll go along with it. Here is a theorem stated in this abused notation.

Theorem. (i) $\Delta c = 0$ for any $c \in \mathbb{R}$

- (ii) $\Delta^m x^m = m!$ for nonnegative integer m
- (iii) $\Delta^m x^n = 0$ for nonnegative integers m, n with m > n

$$Proof.$$
 ...

Falling Factorial Powers

In differential calculus we have $Dx^m = mx^{m-1}$. Computing, $\Delta x^2 = (x+1)^2 - x^2 = 2x + 1 \neq 2x$, we find that the formula for D does not carry over to Δ . However, similar formula holds for another kind of power function.

Let m be a positive integer. For any $x \in \mathbb{R}$, define the mth falling factorial power of x, written $x^{\underline{m}}$, and read x to the m falling, to be

$$x^{\underline{m}} = \overbrace{x(x-1)\cdots(x-m+1)}^{m \text{ factors}}.$$

We define $x^{\underline{0}} = 1$. Note that the familiar factorial function n! can be written $n^{\underline{n}}$.

Theorem. For nonnegative integer m, we have $\Delta x^{\underline{m}} = mx^{\underline{m-1}}$.

$$Proof.$$
 ...

We know that $x^{m+n} = x^m x^n$. What's the corresponding formula for falling powers? Consider the expression x^{m+n} , where m, n are nonnegative integers. It's clear that

$$x^{\underline{m+n}} = x^{\underline{m}}(x-m)^{\underline{n}}.$$

We would like to extend the definition of the falling powers to negative integer exponents so that the above formula holds. Plugging in m = -n in the above formula gives us

$$x^{-n} = \frac{1}{(x+n)^{\underline{n}}} = \frac{1}{(x+1)(x+2)\cdots(x+n)}$$

for positive integer n. We will take this to be the definition of falling negative powers. Using this definition, we find that $x^{\underline{m+n}} = x^{\underline{m}}(x-m)^{\underline{n}}$ for all integers m, n. (Prove!) Even nicer, the last theorem generalizes.

Theorem. For any integer m, we have $\Delta x^{\underline{m}} = mx^{\underline{m-1}}$.

$$Proof.$$
 ...

For a function f and integer m, define $f(x)^{\underline{m}}$ to be

$$f(x)^{\underline{m}} = \begin{cases} f(x)f(x-1)\cdots f(x-m+1) & \text{if } m > 0\\ 1 & \text{if } m = 0\\ \frac{1}{f(x+1)f(x+2)\cdots f(x-m)} & \text{if } m < 0. \end{cases}$$

Theorem. For any integer m and any reals a, b, we have $\Delta(ax+b)^{\underline{m}} = am(ax+b)^{\underline{m-1}}$.

$$Proof.$$
 ...

Exercise Rising factorial power, $x^{\overline{m}}$, is a parallel concept to falling factorial power. Define rising factorial power and find interesting theorems about it.

Polynomials and Stirling Numbers

From the definition of falling factorial powers, we see that every falling power is a polynomial like so

$$x^{\underline{1}} = x$$

$$x^{\underline{2}} = x^{2} - x$$

$$x^{\underline{3}} = x^{3} - 3x^{2} + 2x$$

$$x^{\underline{4}} = x^{4} - 6x^{3} + 11x^{2} - 6x$$

$$x^{\underline{5}} = x^{5} - 10x^{4} + 35x^{3} - 50x^{2} + 24x$$

etc. and using the above identities, we can also write every ordinary power as a polynomial of falling powers like so

$$x = x^{1}$$

$$x^{2} = x^{2} + x^{1}$$

$$x^{3} = x^{3} + 3x^{2} + x^{1}$$

$$x^{4} = x^{4} + 6x^{3} + 7x^{2} + x^{1}$$

$$x^{5} = x^{5} + 10x^{4} + 25x^{3} + 15x^{2} + x^{1}$$

Theorem. Every ordinary polynomial has a unique representation as a polynomial of falling powers. Every polynomial of falling powers has a unique representation as an ordinary polynomial.

Proof. ...
$$\Box$$

The interesting question is: how do we find the coefficients in the representation of these powers? See Spiegel, Solved Problems 1.23–1.25, p.17–19.

The coefficients of the polynomials in the first set of identities are called *Stirling numbers* of the first kind. Spiegel notates them by s_k^n , e.g., $s_2^3 = -3$ since the coefficient of x^2 in the representation of x^3 equals -3. We will use the notation $\begin{bmatrix} n \\ k \end{bmatrix}$ to denote $|s_k^n|$.

The coefficients of the polynomials of falling powers in the second set of identities are called *Stirling numbers of the second kind*. Spiegel notates them by S_k^n , e.g., $S_3^4 = 6$ since the coefficient of $x^{\underline{3}}$ in the representation of x^4 equals 6. We will use the notation $\binom{n}{k}$ to denote S_k^n .

Exponential Functions

In differential calculus we learned that $De^x = e^x$. Technically we say that the function $x \mapsto e^x$ is a fixed-point of the D operator. What is the corresponding formula in discrete calculus? In other words, does the Δ operator have a fixed-point? The answer is yes, the function $x \mapsto 2^x$ is a fixed-point.

Theorem. (i)
$$\Delta c^x = (c-1)c^x$$
 for all $c \in \mathbb{R}$.

(ii)
$$\Delta 2^x = 2^x$$
.

$$Proof.$$
 ...

The Discrete Taylor Formula

Lemma. $E^n f(x) = f(x+n)$ for all $n \in \mathbb{Z}$. In particular, $E^n f(0) = f(n)$.

$$Proof.$$
 ...

Theorem. For all nonnegative integer n,

$$E^{n} = (\Delta + I)^{n} = \sum_{k=0}^{n} \binom{n}{k} \Delta^{k}$$

Proof. The result holds as a result of the Binomial Theorem and that Δ and I commute under composition.

Corollary. For all function f and all nonnegative integer n,

$$f(n) = (\Delta + I)^n f(0) = \sum_{k=0}^n \binom{n}{k} \Delta^k f(0).$$

Proof. Applying the above theorem to f and evaluating the result at 0, we have

$$E^{n}f(0) = (\Delta + I)^{n}f(0) = \sum_{k=0}^{n} {n \choose k} \Delta^{k}f(0).$$

By the above lemma $E^n f(0) = f(n)$. The Corollary results.

Gregory-Newton forward difference interpolation formula

If we know the values of $\Delta^k f(0)$ for all k = 0, 1, 2, ..., n, we can use the discrete Taylor formula to find a polynomial of degree at most n that interpolates f as follows. Define the polynomial P_n by declaring

$$P_n(x) := \sum_{k=0}^n \binom{x}{k} \Delta^k f(0) = \sum_{k=0}^n \frac{x^{\underline{k}} \left(\Delta^k f(0)\right)}{k!}$$

for all real x. Then P_n is a polynomial of degree at most n that interpolates the function f at x = 0, 1, ..., n, i.e., $P_n(x) = f(x)$ for all x = 0, 1, ..., n.

Another application of the fact that $\Delta = E - I$ and that these 3 operators Δ , E, and I commute is the calculation of $\Delta^n f(x)$ in terms of a sum of $f(\cdot)$'s. We have

$$\Delta^n = (E - I)^n = \sum_{k=0}^n \binom{n}{k} E^{n-k} (-I)^k = \sum_{k=0}^n (-1)^k \binom{n}{k} E^{n-k}.$$

For example,

$$\Delta^3 f(x) = f(x+3) - 3f(x+2) + 3f(x+1) - f(x).$$