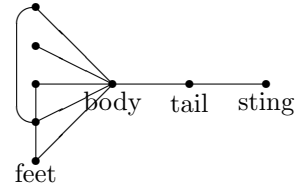


1. (3.x — work alone) A *scorpion* is a graph with three special nodes:

- (a) A *body* which is connected to all other vertices but the sting.
- (b) A *tail* connected only to the body and the sting
- (c) A *sting* connected only to the tail.



All other vertices are called *feet*. The feet may be interconnected arbitrarily, and are connected to the body, but not the tail nor the sting. Given a scorpion on  $n \geq 5$  nodes, find the sting in time  $O(n)$  by asking questions of the form, “Is node  $u$  connected to node  $v$ ?” (In other words, the graph is given as an adjacency matrix already loaded into memory.)

Background: The significance of the scorpion graph is that it provides a counterexample to the conjecture, “Any non-trivial property of undirected graphs is evasive.” A *property* of graphs must be invariant under isomorphism; in other words, it must be independent of the node-labels. Thus examples of non-trivial graph properties are: “ $G$  is connected” or “ $G$  is planar” or “ $G$  has 23 edges”, while “Vertex  $A$  of  $G$  has degree 3” is not a graph property. A trivial graph property is one which is true (or false) for all graphs. A property is evasive if (in the worst case) all entries of an adjacency matrix must be inspected in order to determine if a graph has the property. Virtually all graph properties you would naturally think of are evasive.